

# RTX2018

## Interface Specification

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## 1 Introduction

This document describes the software interface between an application for the RTX2018 system and the DLL that is implementing the functionality and connection to the HW of the system.

### 1.1 Document History

Ver.	Description	Resp.	Date
0.1	Draft version.	LGJ	25-Feb-2019
0.2	Improved draft revision.	Init	xx-mmm-yyyy
1.0	Released after review by xxx, yyy and zzz.	Init	xx-mmm-yyyy

### 1.2 References

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## 2 System Description

The system is based on the Rohde & Schwarz CMW100 tester. The CMW100 is basically a fast AD / DA converter. The CMW100 is connected to a PC with some CMW100 driver software. The CMW100 hardware, PC and CMW100 driver is the real test equipment. On top of this the DECT functionality is added. This is done with a DLL, that offer a set of functions to setup the equipment and make the calculations needed for testing a DECT device. The test application uses this DLL.

An overview of the system is shown in Figure 1.

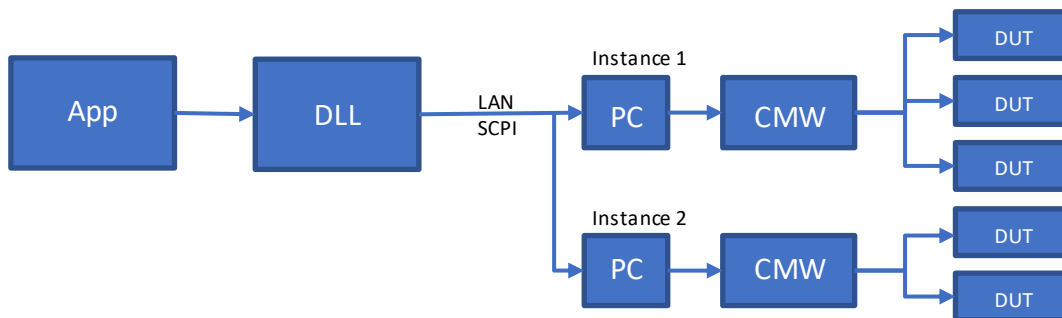


Figure 1: System setup for RTX2018 test equipment

The test application can be programmed in any language that supports use of a Windows DLL.

The test application and DLL can be located and executed on the PC connected to the CMW100 or it can be executed from a remote connection.

## 3 Format of Interfaces, Functions and Types

Communication with a device is done using an *interface*, which is a collection of functions and types.

**Interfaces** are documented using the following format:

<b>Interface:</b>	<b>The name of the interface</b>
<b>Description:</b>	A description of the interface.

All functions and types following an interface specification belong to that interface, until the end of the document or a new interface is specified.

The communication in this interface is function based.

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**Function interfaces** do not use mails for communication. Typically, these interact with the DLL and do not directly communicate with the target. A function is documented like this:

<b>Callx:</b>	<b>The name of the function</b>	
<b>Description:</b>	A description of what the function does	
<b>Return value type:</b>	The type of the return value. This may be a simple type or the name of a composite type, which is documented in the <i>Types</i> section in this document. If a composite type is only used as a call return value, it may be documented immediately after the call documentation.	
<b>Return value description:</b>	A description of the return value	
<b>Parameters:</b>		
<b>Type</b>	<b>Name:</b>	<b>Description:</b>
		Here the types and names of all parameters in the function is described. Types used for parameters are documented elsewhere in this document.

**Type definitions** are documented using one of two similar formats:

<b>TypeNamex:</b>	<b>The name of the defined type</b>
<b>Group:</b>	The kind of type. Typical groups are enumerations, structures, unions, constants, etc.
<b>Description:</b>	A description of the type
<b>Type:</b>	The underlying type, e.g. uint8_t, int32_t, bool etc.
<b>Value:</b>	The value of the type (constants only)

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<b>TypeNamex:</b>	<b>The name of the defined type</b>	
<b>Group:</b>	The kind of type. Typical groups are enumerations, structures, unions, constants, etc.	
<b>Description:</b>	A description of the underlying type	
<b>Code</b>	<b>Description</b>	
Code that defines the members of the type	A description of each member.	

The following sections document the various interfaces used in this system and their functions, and types.

## 4 RTX2018 Interface

### 4.1 Interface Definitions

<b>Interface:</b>	<b>Cmw</b>
<b>Description:</b>	This interface allows applications to use and configure the CWM module to implement the RTX2018 functionality. All functions and types in this interface are prefixed with “Cmw”.

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## 4.2 Enumeration Definitions

<b>TypeName:</b>	<b>Cmw_ErrorType_t</b>	
<b>Group:</b>	Enumeration	
<b>Description:</b>	This type defines the legal error types in the system	
<b>Code</b>	<b>Description</b>	
CMW_ERR_NO_ERROR = 0	No error	
CMW_ERR_RANGE = 1	A value was outside the legal range	
CMW_ERR_UNDERDRIVEN = 2	Input-level too high to perform valid measurements	
CMW_ERR_OVERDRIVEN = 3	Input-level too low to perform valid measurements	
CMW_ERR_UNABLE_TO_CONNECT_CMW = 4	Unable to make connection to the instrument	
CMW_ERR_TIMEOUT = 5	The operation timed out	
CMW_ERR_NOT_IMPLEMENTED = 6	The requested operation is not implemented	
CMW_ERR_NO_DATA_AVAILABLE=7	No signal to analyze	
CMW_ERR_EVAL_WINDOW_VIOLATION=8	Eval-window do not fit in capture window	
CMW_ERR_FILE_NOT_FOUND=9		
CMW_ERR_NO_SYNC_FOUND=10	Not able to find sync in signal	
CMW_ERR_NO_LICENSE_AVAILABLE=11		
CMW_ERR_INVALID_LICENSEFILE=12		
CMW_ERR_LICENSE_EXPIRED=13		
CMW_ERR_UNKNOWN = 14	The request or subcommand was unknown	
CMW_ERR_NO_REPLY = 0x80	The device did not respond to the DLL in time	

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<b>TypeName:</b>	<b>Cmw_StatusType_t</b>	
<b>Group:</b>	Enumeration	
<b>Description:</b>	This type defines the status modes in the system	
<b>Code</b>	<b>Description</b>	
CMW_STATUS_CONNECTED_TO_CMW = 1		
CMW_NO_SIGNAL = 2		
CMW_STATUS_OK = 0	Everything is OK	

<b>TypeName:</b>	<b>Cmw_AnaModType_t</b>	
<b>Group:</b>	Enumeration	
<b>Description:</b>	This type defines the used modulation type in the system	
<b>Code</b>	<b>Description</b>	
GFSK = 0		
PI2_DBPSK = 1		
PI4_DQPSK = 2		
PI8_D8PSK = 3		

<b>TypeName:</b>	<b>Cmw_AnaRefPoint_t</b>	
<b>Group:</b>	Enumeration	
<b>Description:</b>	This type defines the reference point modes for analyzing	
<b>Code</b>	<b>Description</b>	
B0 = 0	Used if B0 is available	
TrigPoint = 1	Used if B0 not defined	
All = 2	All sampled data will be analyzed.	

<b>TypeName:</b>	<b>Cmw_State_t</b>	
<b>Group:</b>	Enumeration	
<b>Description:</b>	This type defines the On/Off state of a feature	
<b>Code</b>	<b>Description</b>	
Off = 0	Feature is disabled	
On = 1	Feature is enabled	

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<b>TypeName:</b>	<b>Cmw_GenPortType_t</b>	
<b>Group:</b>	Enumeration	
<b>Description:</b>	This type defines the port numbering for the generator	
<b>Code</b>	<b>Description</b>	
Port1 = 0x01	Value for port 1	
Port2 = 0x02	Value for port 2	
Port3 = 0x04	Value for port 3	
Port4 = 0x08	Value for port 4	
Port5 = 0x10	Value for port 5	
Port6 = 0x20	Value for port 6	
Port7 = 0x40	Value for port 7	
Port8 = 0x80	Value for port 8	

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### 4.3 Type Definitions

<b>Type Name:</b>	<b>Cmw_AnaMeasDataRetType_t</b>	
<b>Group:</b>	Struct	
<b>Description:</b>	This type defines the calculated results based on one set of samples.	
<b>Code</b>	<b>Description</b>	
double PhaseOffset;	[Rad]. Initial relative phase orientation in demodulated signal. Only useful for debugging purposes.	
double FreqOffset;	[Hz] Frequency offset of the analyzed signal.	
uint64_t SampleOffset;	[Samples].	
uint64_t B0SymbolOffset;	[Symbols] Number of symbol times from start of capture window only location of the b0. Symbol.	
uint64_t B0SampleOffset;	Samples. Sample number of the capture window where the center of b0 is.	
int64_t MinFreqDeviation;	[Hz] Frequency deviation of the FM demodulated signal. Only valid result if modulation is GFSK.	
int64_t MaxFreqDeviation;	[Hz] Frequency deviation of the FM demodulated signal. Only valid result if modulation is GFSK.	
double EVM;	[dB]. RMS EVM of the signal. Only valid for PI2_DBPSK, PI4_DQPSK, PI8_D8PSK,	
double EVMPeak;	[dB]. Peak EVM of the signal. Only valid for PI2_DBPSK, PI4_DQPSK, PI8_D8PSK,	
double Power;	[dBm]. TX power level of the signal.	
Cmw_ErrorType_t Error;		

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<b>TypeName:</b>	<b>Cmw_BlockDataType_t</b>	
<b>Group:</b>	Struct	
<b>Description:</b>	This type defines data that controls copying a big data block in smaller chunks.	
<b>Code</b>	<b>Description</b>	
uint32_t Start;	The index of the next chunk in the big block	
uint8_t Size;	The size of the chunk	
double Time[100];	Sample time	
double IData[100];	The I data of the chunk	
double QData[100];	The Q data of the chunk	
bool Done;	If true, this chunk is the last one	
Cmw_ErrorType_t Error;		

<b>TypeName:</b>	<b>Cmw_GeneralRetType_t</b>	
<b>Group:</b>	Struct	
<b>Description:</b>	General return type used by functions where no data is returned, but only the error code.	
<b>Code</b>	<b>Description</b>	
Cmw_ErrorType_t Error;		

<b>TypeName:</b>	<b>Cmw_InitRetType_t</b>	
<b>Group:</b>	Struct	
<b>Description:</b>	Return type for the initialization call.	
<b>Code</b>	<b>Description</b>	
uint8_t Instance;	Instance number to be used in rest of the interface	
char DevName[256];	Name, serial number and version of the attached instrument	
char DLLName[256];	Name and version of the attached instrument	
Cmw_ErrorType_t Error;		

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<b>TypeName:</b>	<b>Cmw_GetPowerRetType_t</b>	
<b>Group:</b>	Struct	
<b>Description:</b>	Return type for get power call	
<b>Code</b>	<b>Description</b>	
double Power;	Average power in measurement window	
Cmw_ErrorType_t Error;		

#### 4.4 Function Definitions

<b>Call:</b>	<b>Cmw_Init</b>	
<b>Description:</b>	Initialize the Cmw interface	
<b>Return value type:</b>	Cmw_InitRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE CMW_ERR_UNABLE_TO_CONNECT_CMW	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
char*	SocketServerIP	IP-address of socket server
char*	SocketServerName	DNS name of socket server
uint16_t	Port	IP port of socket server

<b>Call:</b>	<b>Cmw_Close</b>	
<b>Description:</b>	Closes connection to CMW	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	

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<b>Call:</b>	<b>Cmw_GetSystemInfo</b>	
<b>Description:</b>	Reads information about the tester and DLL	
<b>Return value type:</b>	Cmw_InitRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE CMW_ERR_UNABLE_TO_CONNECT_CMW	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	

<b>Call:</b>	<b>Cmw_SetAnaFrequency</b>	
<b>Description:</b>	Set frequency for the analyzer. Range: 0 – 6 GHz Default: 1 GHz	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint64_t	Freq	[Hz] Frequency to be set

<b>Call:</b>	<b>Cmw_SetGenFrequency</b>	
<b>Description:</b>	Set frequency for the generator. Range: 0 – 6 GHz Default: 1 GHz	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint64_t	Freq	[Hz] Frequency to be set

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<b>Call:</b>	<b>Cmw_SetGenPower</b>	
<b>Description:</b>	Set generator power Range: -134 – -15 dBm Default_ -134 dBm	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
double	Power	[dBm] Generatorpower to be set

<b>Call:</b>	<b>Cmw_LoadGeneratorModFile</b>	
<b>Description:</b>	Specify the path and filename of the file to be for modulating the generator	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_TIMEOUT CMW_ERR_FILE_NOT_FOUND	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
const char*	ModulationFilePa th	Path of the file to be loaded into the CMW. ("C:\RTX2018\")
const char*	ModulationFile	Filename of the file to be loaded into the CMW.

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<b>Call:</b>	<b>Cmw_SetGeneratorPort</b>	
<b>Description:</b>	Sets the output port for the generator. More than one port can be active at same time. Default: 0	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_TIMEOUT CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
Cmw_GenPortType_t	Port	Sets the ports on and off. (0b00000100 set port 3 on)

<b>Call:</b>	<b>Cmw_SetGeneratorState</b>	
<b>Description:</b>	Sets the state of the generator. This command controls all the ports. Default: Off	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_TIMEOUT	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
Cmw_State_t	State	Sets the generator state to On or Off

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<b>Call:</b>	<b>Cmw_SetAnaModulationType</b>	
<b>Description:</b>	Sets the modulation type of the analyzer Default: PI2_DBPSK	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
Cmw_AnaModType_t	ModulationType	

<b>Call:</b>	<b>Cmw_SetAnaCaptureWindow</b>	
<b>Description:</b>	Defines the window where the signal is sampled. GateDelay: Range: -1000 – -10 us Default: -40; GateTime: Range: 10 – 1000 us Default: 400 us	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
int64_t	GateDelay	[us] Start of capture time relative to trigger point.
uint64_t	GateTime	[us] Length of capture time.

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<b>Call:</b>	<b>Cmw_SetAnaAnalyzerWindow</b>	
<b>Description:</b>	Defines the part the capture window used to analyze signal. RefPoint: Default: All GateDalay: Range: -1000 – 1000 us Default: 0; GateTime: Range: 10 – 1000 us Default: 350 us	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
Cmw_AnaRefPoint_t	RefPoint	
int64_t	GateDelay	[us]
uint64_t	GateTime	[us]

<b>Call:</b>	<b>Cmw_SetAnaTrigOffset</b>	
<b>Description:</b>	Defines the offset to expected power to trig a measurement sequence Range: -50 – 0 dB Default: 0 dB	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
double	TrigOffset	dB

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<b>Call:</b>	<b>Cmw_SetAnaTrigGap</b>	
<b>Description:</b>	Defines the time where power has to be below trigger offset to allow new trigger. Range: 0 – 1000 us (if 0 us, the first coming trigger event is used.) Default: 10 us	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint64_t	TrigGap	us

<b>Call:</b>	<b>Cmw_SetAnaExpPowLevel</b>	
<b>Description:</b>	Sets the powerlevel at which it is expected that the DUT transmits . Range: -60 – 50 dBm Default: 0	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
double	PowLevel	[dBm]

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<b>Call:</b>	<b>Cmw_SetAnalyzerPort</b>	
<b>Description:</b>	Sets the RF port o the CMW to be used for the analyzer. Only one port can be active. Range: 1 – 8 Default: 1	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint8_t	Port	

<b>Call:</b>	<b>Cmw_SetAnaSymbolRate</b>	
<b>Description:</b>	Sets the symbol rate of the sampled signal to be analyzed. The DLL operates with an oversampling factor of 16. Range: 0 – 2MHz Default: 1152000 Hz	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint64_t	SymbolRate	[Hz]

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<b>Call:</b>	<b>Cmw_SetSyncWord</b>	
<b>Description:</b>	Defines the length and content of the Synchronization word. Syncword: Default: 0x51975555 NumberOfBitsInSyncword: Range: 0 – 64 Default: 32	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>	CMW_ERR_NO_ERROR CMW_ERR_RANGE	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint64_t	SyncWord	The syncword that the DLL uses to determines the position of bit 0.
uint64_t	NumberOfBitsInSyncword	Number of bits in synchronization word. Max value: 64

<b>Call:</b>	<b>Cmw_AnaGetMeasData</b>	
<b>Description:</b>	Capture and analyze the signal. Calculated values are reported in the return structure. If signal is captured, it can be re-analyzed if UpdateSignal is low.	
<b>Return value type:</b>	Cmw_AnaMeasDataRetType_t	
<b>Return value description:</b>		
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
bool	UpdateSignal	Used to control when to capture new signal.

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<b>Call:</b>	<b>Cmw_AnaGetPower</b>	
<b>Description:</b>	Capture and calculate power of captured signal	
<b>Return value type:</b>	Cmw_GetPowerRetType_t	
<b>Return value description:</b>	Power is returned in dBm	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
bool	UpdateSignal	Used to control when to capture new signal

<b>Call:</b>	<b>Cmw_AnaSetSignalDataBlock</b>	
<b>Description:</b>	Download signal to be analyzed from the client. By loading a signal with this function and afterwards analyzing it with "UpdateSignal" equal to 0, it is possible to analyze stored signals. Mainly used for debug purposes.	
<b>Return value type:</b>	Cmw_GeneralRetType_t	
<b>Return value description:</b>		
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
Cmw_BlockDataType_t	SignalBlock	Chunk of data. Max 100 records per transaction.
uint16_t	Blockno	The index of the chunk. Must start from 0 and increment by one for each call.

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<b>Call:</b>	<b>Cmw_AnaGetDemodDataBlock</b>	
<b>Description:</b>	Upload one big block of data to the client	
<b>Return value type:</b>	Cmw_BlockDataType_t	
<b>Return value description:</b>	The next chunk of data	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint16_t	Blockno	The index of the chunk. Must start from 0 and increment by one for each call.

<b>Call:</b>	<b>Cmw_AnaGetPowerDataBlock</b>	
<b>Description:</b>	Upload one big block of data to the client	
<b>Return value type:</b>	Cmw_BlockDataType_t	
<b>Return value description:</b>	The next chunk of data	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint16_t	Blockno	The index of the chunk. Must start from 0 and increment by one for each call.

<b>Call:</b>	<b>Cmw_AnaGetIQDataBlock</b>	
<b>Description:</b>	Upload one big block of data to the client	
<b>Return value type:</b>	Cmw_BlockDataType_t	
<b>Return value description:</b>	The next chunk of data	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint16_t	Blockno	The index of the chunk. Must start from 0 and increment by one for each call.

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<b>Call:</b>	<b>Cmw_AnaGetDemodulatedBitsBlock</b>	
<b>Description:</b>	Upload one big block of data to the client.	
<b>Return value type:</b>	Cmw_BlockDataType_t	
<b>Return value description:</b>	The next chunk of data	
<b>Parameters:</b>		
<b>Type</b>	<b>Name</b>	<b>Description</b>
uint8_t	Instance	
uint16_t	Blockno	The index of the chunk. Must start from 0 and increment by one for each call.

## 5 Read Back of Large Data Amounts

As this DLL is intended to also be used with “Managed memory” programming tools as Python and .Net the DLL does not use pointers to memory locations for return large data sets.

As there is a limited amount of data size available for the return structure, the data will need to be read back using several calls to the function to obtain the data in chunks.

This method is valid for the following functions:

- Cmw\_AnaGetDemodulatedBitsBlock
- Cmw\_AnaGetIQDataBlock
- Cmw\_AnaGetPowerDataBlock
- Cmw\_AnaGetDemodDataBlock
- Cmw\_AnaSetSignalDataBlock

The first call to one of these functions is populated with a Blockno of 0.

The return structure for this function call includes both part of the data (I and Q data) together with the length of the data.

Besides the number for the next chunk is included. This can be used as calling argument for the next call the function.

When there is no more data available, the “Done” field is asserted.

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